

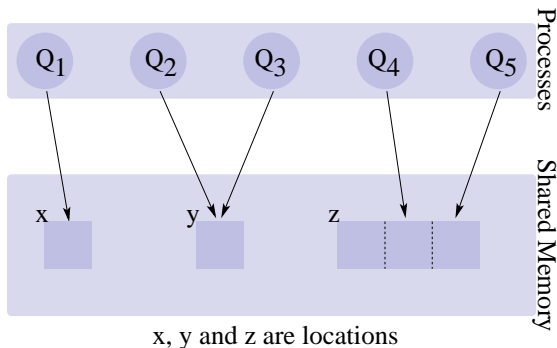
# Directed Algebraic Topology and Concurrency

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GEOCAL 2006 Marseille

# Concurrency and Geometry ?

shared memory style



Not sequential programs, bad states, chaotic behavior

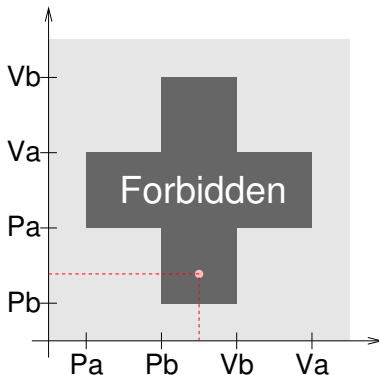
⇒ Need for synchronizations ⇒ Need for locks

⇒ deadlocks might appear.

# Geometry

“progress graphs” E.W.Dijkstra'68 (later V.Pratt, R. van Glabbeek'91)

$T1=Pa.Pb.Vb.Va$  in parallel with  $T2=Pb.Pa.Va.Vb$

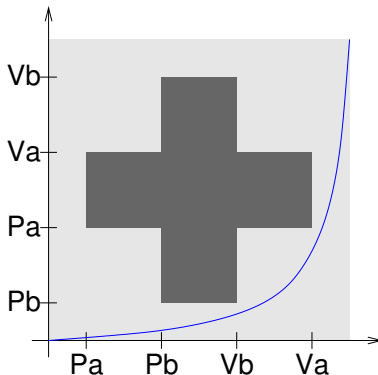


“Continuous model”:  $x_i$  = local time; dark grey region = forbidden!

# Execution paths

are continuous

$T1=Pa.Pb.Vb.Va$  in parallel with  $T2=Pb.Pa.Va.Vb$



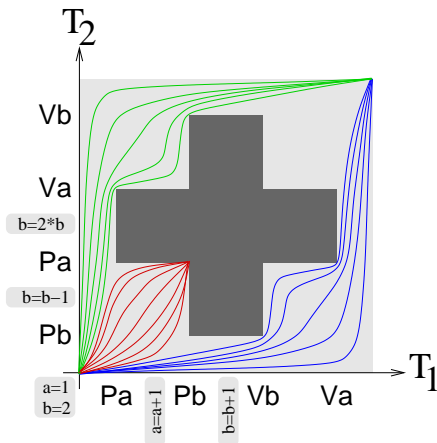
Traces are continuous paths increasing in each coordinate: [dipaths](#).

# Classes of equivalent dipaths up to dihomotopy

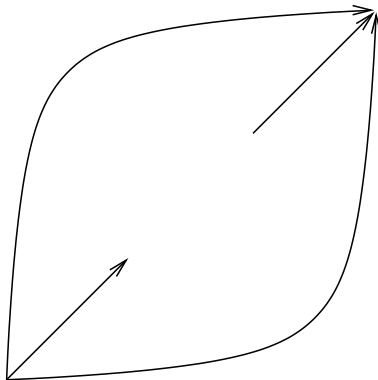
T1 gets a and b before T2  $\Rightarrow a=2$  and  $b=4$

T2 gets b and a before T1  $\Rightarrow a=2$  and  $b=3$

Each of T1 and T2 gets a resource  
 $\Rightarrow$  Deadlock with  $a=2$  and  $b=1$



Ideally...  
not quite true though



We will get back to this later.

# A typical object of study

fundamental category  $\vec{\pi}_1(\vec{X})$  of a pospace  $\vec{X}$

- its objects are the points of  $X$ ,
- its morphisms are the classes of dipaths up to dihomotopy:  
a morphism from  $x$  to  $y$  is a dihomotopy class  $[\alpha]$  of a dipath  $\alpha$  going from  $x$  to  $y$ .

## A detailed example (1)

square with centered hole

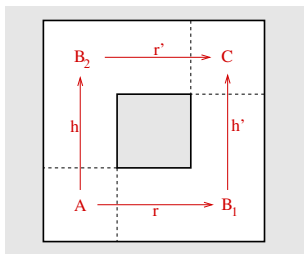
$x \in$	$y \in$	$\vec{\pi}_1(\vec{X})[x, y]$
A	A	$\{\sigma_{x,y}\}$
$B_1$	$B_1$	$\{\sigma_{x,y}\}$
$B_2$	$B_2$	$\{\sigma_{x,y}\}$
C	C	$\{\sigma_{x,y}\}$
A	$B_1$	$\{r_{x,y}\}$
A	$B_2$	$\{h_{x,y}\}$
$B_1$	C	$\{h'_{x,y}\}$
$B_2$	C	$\{r'_{x,y}\}$
$B_1$	$B_2$	$\emptyset$
$B_2$	$B_1$	$\emptyset$
A	C	$\{u_{x,y}, d_{x,y}\}$

With

$$r'_{y,z} \circ h_{x,y} = u_{x,z}, \quad h'_{y,z} \circ r_{x,y} = d_{x,z}$$

and 3 points  $x, y, z$  of the square such that  $x \sqsubseteq y \sqsubseteq z$ ;

if  $x \not\sqsubseteq y$  then  $\vec{\pi}_1(\vec{X}) = \emptyset$ .



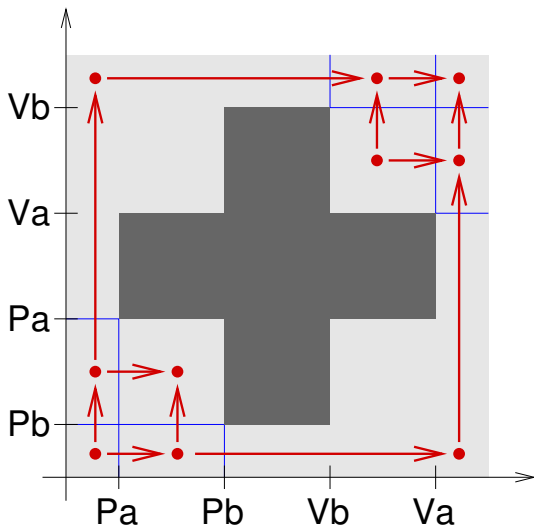
## A detailed example (2)

the previous calculation suggests that

- we have a partition  $A, B_1, B_2, C$  of the objects of  $\vec{\pi}_1(\vec{X})$ ,
- any arrow of  $\vec{\pi}_1(\vec{X})$  can be given a “type” ( $\sigma, h, h', r, r', u$  or  $d$ ) according to the components its extremities  $x$  and  $y$  belong to,
- the type  $\sigma$  is “neutral” in the sense that  $\sigma_{y,z} \circ \sigma_{x,y} = \sigma_{x,z}$
- the map which sends
  - any object  $x$  of  $\vec{\pi}_1(\vec{X})$  to its component ( $A, B_1, B_2$  or  $C$ )
  - any morphism  $\alpha$  to its “type” ( $\sigma, h, h', r, r', u$  or  $d$ )

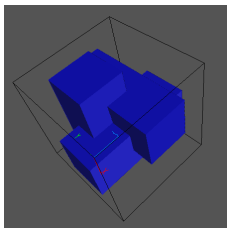
is both an **equivalence** and a **fibration** and its codomain is, by definition, the **category of components** of  $\vec{X}$ .

# The category of components of the swiss flag

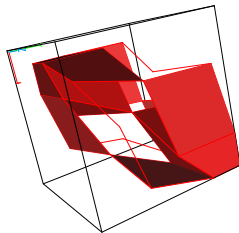


# The components category of the 3 philosophers

non-orthogonal representation

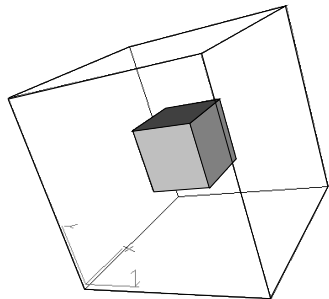


the pospace

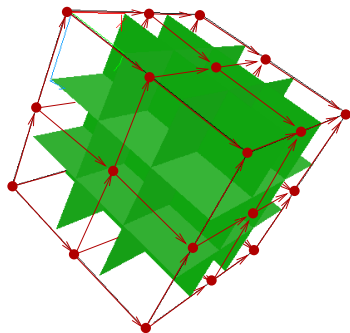


its category of components

# The components category of a 2-semaphore



the pospace



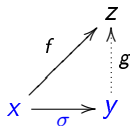
its category of components

# Yoneda morphism

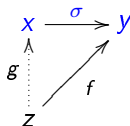
axiomatizing the preservation of the future and the past (1)

Let  $\mathcal{C}$  be a small category. A *Yoneda* morphism  $\sigma$  is an element of  $\mathcal{C}[x, y]$  such that for all object  $z$  of  $\mathcal{C}$ ,

**future** if  $\mathcal{C}[y, z] \neq \emptyset$  then for all  $f \in \mathcal{C}[x, z]$ , there is a unique  $g \in \mathcal{C}[y, z]$  such that



**past** if  $\mathcal{C}[z, x] \neq \emptyset$  then for all  $f \in \mathcal{C}[z, y]$ , there is a unique  $g \in \mathcal{C}[z, x]$  such that

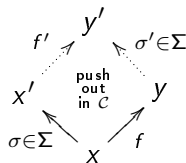
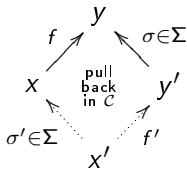


# Yoneda system of a small category $\mathcal{C}$

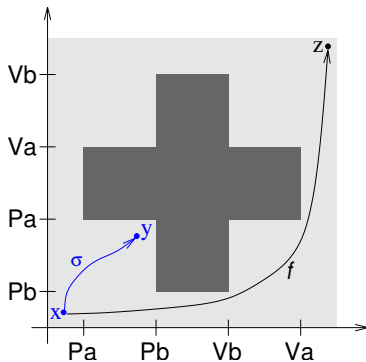
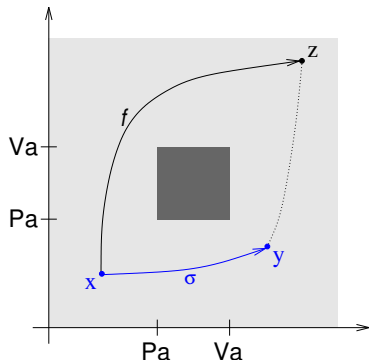
axiomatizing the preservation of the future and the past (2)

A collection  $\Sigma$  of morphisms of  $\mathcal{C}$  such that:

- ①  $\Sigma$  is stable under composition,
- ②  $\Sigma$  contains all the isomorphisms of  $\mathcal{C}$ ,
- ③ all the elements of  $\Sigma$  are *Yoneda* morphisms and
- ④  $\Sigma$  is stable under **change** and **cochange** of base.



## Examples

of morphisms which do not belong to a *Yoneda* system

# Lifting properties of the component category

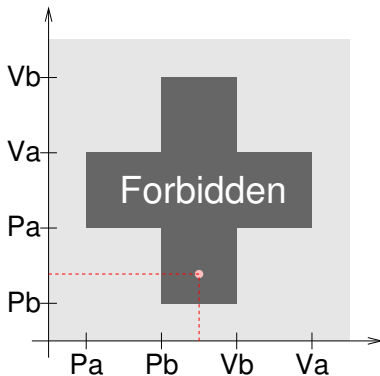
Let  $\mathcal{C}$  be a category in which all endomorphisms are identities. Then there is a maximal Yoneda-system  $\Sigma$  in  $\mathcal{C}$ . Furthermore, let  $C_1, C_2 \subset Ob(\mathcal{C})$  denote two components such that the set of morphisms (in  $\mathcal{C}/\Sigma$ ) is *finite*. Then, for every  $x_1 \in C_1$  there exists  $x_2 \in C_2$  such that the quotient map

$$\mathcal{C}(x_1, x_2) \rightarrow \mathcal{C}/\Sigma(C_1, C_2), f \mapsto [f]$$

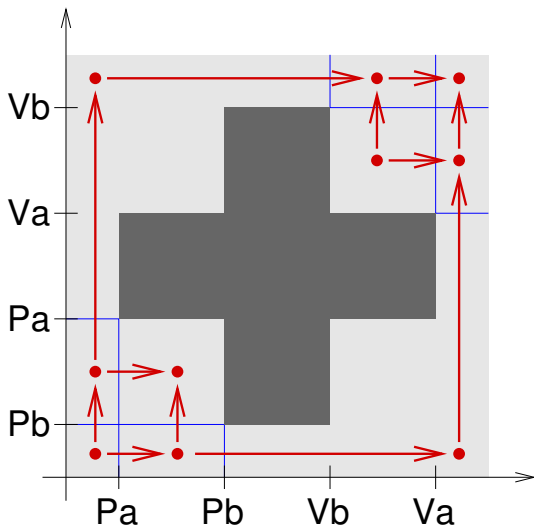
is *bijective*.

# Getting back to the swiss flag

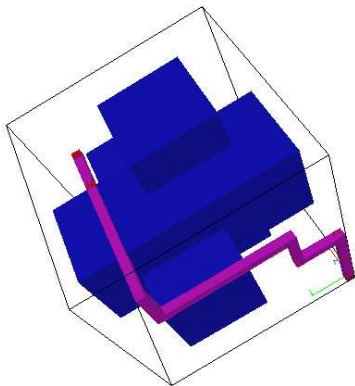
$Pa.Pb.Vb.Va \mid Pb.Pa.Va.Vb:$



## Its component category



# Discretisation of paths



$3P(c); 3P(a); 2P(b); 3V(c); 2P(c); 2V(b);$   
 $2V(c); 3V(a); 1P(a); 1P(b); 1V(a); 1V(b);$

# Fundamental theorem (E. Haucourt)

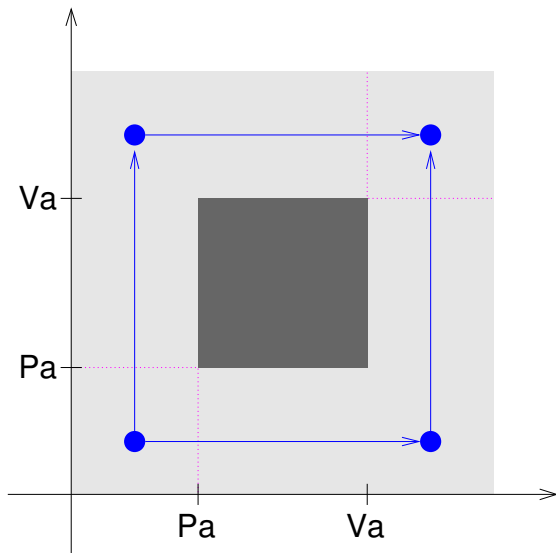
fractions vs quotients

Let  $\mathcal{C}$  be a small loop-free category and  $\Sigma$  a *Yoneda* system of  $\mathcal{C}$ , then

- ① the collection  $\Sigma$  is pure in  $\mathcal{C}$ ,
- ② the small category  $\mathcal{C}/\Sigma$  is loop-free,
- ③ the small categories  $\mathcal{C}[\Sigma^{-1}]$  and  $\mathcal{C}/\Sigma$  are equivalent and
- ④ the category  $\mathcal{C}[\Sigma^{-1}]$  is fibered over  $\mathcal{C}/\Sigma$ .
- ⑤ Seifert/Van Kampen on component categories

extension and improvement of *Components of the Fundamental Category* - APCS 04

## Example



# Components of compact pospaces

## statement

- If  $\vec{K}$  is a compact pospace such that any pair of element of  $K$  has an upper/lower bound, then  $\vec{K}$  has a greatest/least element.
- If  $\vec{K}$  is a compact pospace, then any component of  $\vec{\pi}_1(\vec{K})$  has both a **greatest lower bound** and an **least upper bound** in  $(|K|, \sqsubseteq)$ .

# Future components

Or how to distinguish states by their future (up to dihomotopy)

Let  $\mathcal{C}$  be a small category,  $\Sigma \subseteq Mo(\mathcal{C})$  is a *Yoneda-f-system* iff (by definition)  $\Sigma$  is stable under composition (of  $\mathcal{C}$ ) and satisfies

- all  $\sigma$  in  $\Sigma$  are epis in  $\mathcal{C}$
- $\Sigma$  is stable under pushout (with any morphism in  $\mathcal{C}$ )
- If there is  $u : \beta \rightarrow \gamma$  in  $\mathcal{C}$ , then for all  $\sigma : \alpha \rightarrow \beta$  in  $\Sigma$ , and all  $f : \alpha \rightarrow \gamma$  in  $\mathcal{C}$ ,  $f$  factors through  $\sigma$ , that is, there exists  $h : \beta \rightarrow \gamma$  such that the following diagram commutes



## Past components

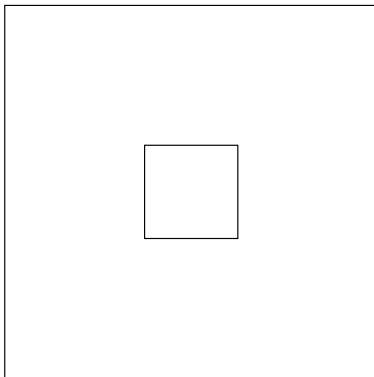
Or how to distinguish state up by their past (up to dihomotopy)

Let  $\mathcal{C}$  be a small category,  $\Sigma \subseteq Mo(\mathcal{C})$  is a *Yoneda-p*-system iff (by definition)  $\Sigma$  is stable under composition (of  $\mathcal{C}$ ) and satisfies

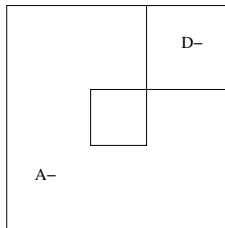
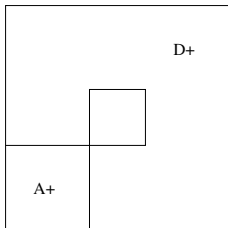
- all  $\sigma$  in  $\Sigma$  are monos in  $\mathcal{C}$
- If there is  $u : \beta \rightarrow \gamma$  in  $\mathcal{C}$ , then for all  $\sigma : \alpha \rightarrow \beta$  in  $\Sigma$ , and all  $f : \alpha \rightarrow \gamma$  in  $\mathcal{C}$ ,  $f$  factors through  $\sigma$ , that is, there exists  $h : \beta \rightarrow \gamma$  such that the following diagram commutes



# Example



# Its future and past components



## An extra condition on components (?)

(Conjecture): automatically true in the PV case

- Let  $\mathcal{D}$  be the category whose objects are  $X, X_0, X_1, \dots, X_n, \dots$ , and whose only morphisms are of the form  $X \rightarrow X_i$  ( $i \geq 0$ ).
- Let  $F$  be a functor from  $\mathcal{D}$  to a category  $\mathcal{C}$ .
- We call infinite pushout the colimit of  $F(\mathcal{D})$  in  $\mathcal{C}$ , when it exists.

Ask for future (resp. past) components to have infinite pushouts (resp. pullbacks).

## Extension of the lifting property

With this extra property, we have both for past and future components:

- the lifting property holds
- even if the set of morphisms (in  $\mathcal{C}/\Sigma$ ) between two objects is not finite.

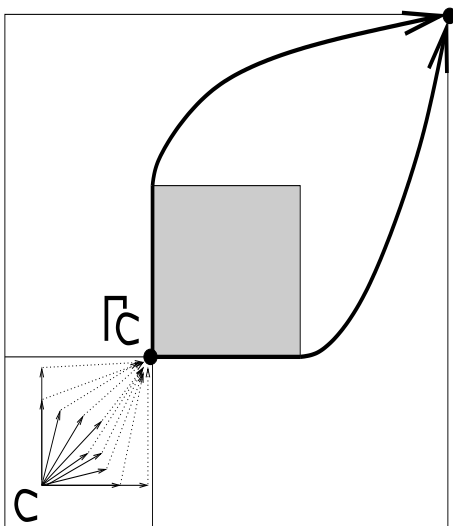
# Orthogonal subcategories

See e.g. Borceux

Let  $\mathcal{C}$  be a category and  $\Sigma$  a class of morphisms of  $\mathcal{C}$ . By the orthogonal subcategory of  $\mathcal{C}$  determined by  $\Sigma$ , we mean the full subcategory  $\mathcal{C}_\Sigma$  of  $\mathcal{C}$ , whose objects are those  $X \in \mathcal{C}$  such that  $s \perp X$  for every  $s \in \Sigma$ , i.e., such that for every  $s : A \rightarrow B \in \Sigma$ , for every morphism  $f : A \rightarrow X$ , there exists a unique morphism  $b : B \rightarrow X$  such that  $b \circ s = f$ .

$$\begin{array}{ccc}
 A & \xrightarrow{s \in \Sigma} & B \\
 \downarrow \forall f \in \mathcal{C} & \swarrow \exists! b & \\
 X & & 
 \end{array}$$

# The orthogonal subcategory of $\Sigma_+$ is reflective



# Theorem

Let  $\Sigma$  be the inessential morphisms in the future, in the category  $\mathcal{C} = \vec{\pi}_1(\vec{X})$  for some local po-space  $X$ .

Suppose that  $\Sigma$  has infinite pushouts then

$\mathcal{C}_\Sigma$  is reflective in  $\vec{\pi}_1(\vec{X})$ .

# Sketch of proof

By definition of the orthogonal subcategory:

- we have an obvious inclusion functor  $I$  from  $\mathcal{C}_\Sigma$  to  $\mathcal{C}$ .
- To prove that we have a reflective subcategory, we need to construct the left adjoint to  $\Gamma \dashv I$ .

# Sketch of proof

- Let  $C \in \mathcal{C}$ . For every pair  $(s, f)$  where  $s : S \rightarrow T \in \Sigma$  and  $f : S \rightarrow C \in \mathcal{C}$ ,
- by the properties of  $\Sigma$ , we know we have a pushout diagram (we call it a  $(s, f)$  pushout square):

$$\begin{array}{ccc}
 S & \xrightarrow{s \in \Sigma} & T \\
 f \downarrow & & \downarrow g_{sf} \\
 C & \xrightarrow[t_{sf} \in \Sigma]{\text{---}} & P_{sf}
 \end{array}$$

where  $t_{sf} \in \Sigma$ .

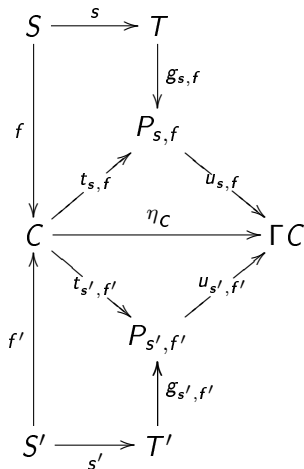
## Sketch of proof

Consider now the diagram composed of all  $t_{sf}$  for all pairs  $(s, f)$  which is small since  $\Sigma$  is a set, thus its colimit  $(\Gamma C, (u_{sf})_{sf})$  exists in  $\underline{\Sigma}$  and provide  $\Gamma C \in \Sigma$ .

We have defined the object part of  $\Gamma$ . Now we construct a family of morphisms of  $\mathcal{C}$ , denoted  $(\gamma_C)_{C \in \text{Ob } \mathcal{C}}$ , that will be the unit of the adjunction.

# Sketch of a proof

Let us determine  $\gamma_C : C \rightarrow \Gamma C$ . Given two  $(s, f)$ -pushout squares, by definition of a colimit, we have  $u_{s,f} \circ t_{s,f} = u_{s',f'} \circ t_{s',f'}$ , hence we can set  $\gamma_C := u_{s,f} \circ t_{s,f}$  since it does not depend on the  $(s, f)$ -pushout square we have chosen.  $\gamma_C \in \Sigma$  for it is given by the composite of two morphisms of  $\Sigma$ .



# Sketch of proof

We determine the morphism part of  $\Gamma$ , this construction will implicitly prove that  $\gamma$  is an adjunction from  $Id_C$  to  $I \circ \Gamma$ . Let  $h : C^1 \rightarrow C^2$ . For each pushout square

$$\begin{array}{ccc}
 S & \xrightarrow{s} & T \\
 f \downarrow & & \downarrow g_{s,f}^1 \\
 C^1 & \xrightarrow{t_{s,f}^1} & P_{s,f}^1
 \end{array}$$

# Sketch of proof

We have the pushout diagram (since  $t_{s,f}^1 \in \Sigma$ ):

$$\begin{array}{ccc}
 C^1 & \xrightarrow{t_{s,f}^1} & P_{s,f}^1 \\
 \downarrow h & & \downarrow g_{t_{s,f}^1, h}^2 \\
 C^2 & \xrightarrow{t_{s,f,h}^2} & P_{t_{s,f,h}^1}^2
 \end{array}$$

## Sketch of proof

Then, using the factorisation of the unit (on  $C^1$  and  $C^2$ ) we have:

$$\begin{array}{ccccc}
 C^1 & \xrightarrow{t_{s,f}^1} & P_{s,f}^1 & \xrightarrow{u_{s,f}^1} & \Gamma(C^1) \\
 \downarrow h & & \downarrow g_{t_{s,f,h}^2} & & \\
 C^2 & \xrightarrow{t_{t_{s,f,h}^1}^2} & P_{t_{s,f,h}^1}^2 & \xrightarrow{u_{t_{s,f,h}^1}^2} & \Gamma(C^2)
 \end{array}$$

# Sketch of proof

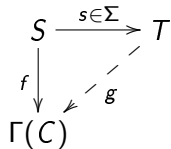
Since  $u_{s,f}^1$  is in  $\Sigma$ , it is invertible in the future (and there is a map from  $\Gamma(C^1)$  to  $\Gamma(C^2)$  because of the universal property of the colimit for  $\Gamma(C^2)$ ), giving the map  $\Gamma(h)$  making the following diagram commute:

$$\begin{array}{ccccc}
 C^1 & \xrightarrow{t_{s,f}^1} & P_{s,f}^1 & \xrightarrow{u_{s,f}^1} & \Gamma(C^1) \\
 \downarrow h & & \downarrow g_{t_{s,f,h}^2} & & \downarrow \Gamma(h) \\
 C^2 & \xrightarrow{t_{s,f,h}^2} & P_{t_{s,f,h}^1}^2 & \xrightarrow{u_{t_{s,f,h}^1}^2} & \Gamma(C^2)
 \end{array}$$

# Sketch of proof

Now we prove that  $\forall C \in \mathcal{C}, \Gamma(C) \in \mathcal{C}_\Sigma$ .

Given  $(s, f)$  with  $s : S \rightarrow T \in \Sigma$ ,  $\text{src}(f) = S$  and  $\text{tgt}(f) = \Gamma(C)$ , we have a  $g$  making the right side diagram commutative. Precisely,  $g := u_{sf} \circ g_{sf}$ , indeed,  $u_{sf} \circ g_{sf} \circ s = u_{sf} \circ t_{sf} \circ f = \gamma_C \circ f$ .



## Sketch of proof

- The uniqueness of  $g$  is due to the bijectivity of  $\gamma \in \mathcal{C}[S, T] \longrightarrow \gamma \circ s \in \mathcal{C}[S, \Gamma(C)]$ , because  $s$  is inessential in the future.
- Thus,  $s \perp \Gamma(C)$  and  $\Gamma(C)$  is in the orthogonal subcategory determined by  $\Sigma$ .

# Sketch of proof

Conversely, suppose that  $X \in \mathcal{C}_\Sigma$ . Given  $(s, f)$  with  $s : S \rightarrow T \in \Sigma$ ,  $\text{src}(f) = S$  and  $\text{tgt}(f) = X$ , we have a unique  $g$  making the right side diagram commutative, which is in fact necessarily the pushout square given by the definition of  $\Sigma$ .

$$\begin{array}{ccc}
 S & \xrightarrow{s \in \Sigma} & T \\
 f \downarrow & & \downarrow g \\
 X & \xrightarrow{id_X} & X
 \end{array}$$

# Sketch of proof

With the notation introduced at the beginning of the proof,

- $g_{s,f} = g$  and  $t_{s,f} = id_X$ .
- But then the colimit of such pushout squares, defining  $(\Gamma(X), u_{s,f})$  is the colimit of the family  $(id_X)_{\{(s,f) \text{ with } s:S \rightarrow T \in \Sigma, \text{ src}(f)=S \text{ and tgt}(f)=X\}}$ .
- Hence  $u_{s,f} \cong id_X$  for all such pairs  $(s, f)$  and  $\Gamma(X) \cong X$  in  $\mathcal{C}$ .

# Sketch of proof

The last part of the proof consists in seeing that

$$\alpha \in \mathcal{C}_\Sigma[\Gamma(C), D] \longmapsto I(\alpha) \circ \gamma_C \in \mathcal{C}[C, I(D)]$$

is a bijection, where  $\gamma_C : C \rightarrow \Gamma C$  is the canonical morphism given by the colimit.

# Sketch of proof

Given  $D \in \mathcal{C}_\Sigma$  and  $m : C \rightarrow D$ , we must find a unique  $n : \Gamma C \rightarrow D$  such that  $n \circ \gamma_C = m$ .

- As  $D \in \mathcal{C}_\Sigma$ , it is orthogonal to all morphisms  $s \in \Sigma$ .
- In particular, for all pairs  $(s, f)$  as above, there exists a unique  $b_{sf}$  such that  $b_{sf} \circ s = m \circ f$ .
- By the pushout property defining  $P_{sf}$  we deduce that there is a unique morphism  $a_{sf} : P_{sf} \rightarrow D$  such that  $a_{sf} \circ t_{sf} = m$  and  $a_{sf} \circ g_{sf} = b_{sf}$ .

## Sketch of proof

- This is done for all pairs  $(s, f)$ .
- Hence by the colimit property defining  $\Gamma C$ , we find a unique morphism  $n : \Gamma C \rightarrow D$  such that  $n \circ u_{sf} = \alpha_{sf}$ .
- Hence

$$\begin{aligned}n \circ \gamma_C &= n \circ u_{sf} \circ t_{sf} \\ &= \alpha_{sf} \circ t_{sf} \\ &= m\end{aligned}$$

which ends the proof.

## Relationship with Marco Grandis work

- Equivalences in the past and in the future
- When two categories are (resp. past) future equivalent, what we have seen provides a common (co-) reflective category

# Generic segment of $\mathbb{C}$

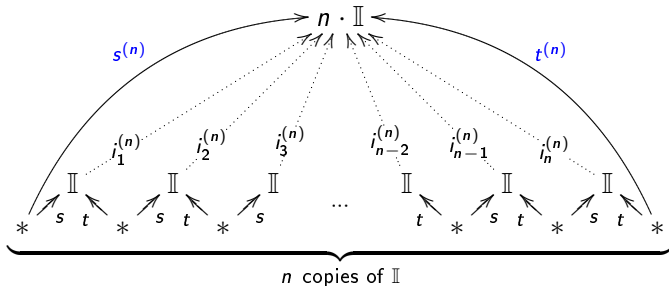
axiomatizing the notion of *Moore* paths (1)

A **generic segment** of  $\mathbb{C}$  is a triple  $(\mathbb{I}, s, t)$  where  $\mathbb{I}$  is an object of  $\mathbb{C}$  and  $s, t$  two points of  $\mathbb{I}$  such that:

- 1 for any automorphism  $\phi$  of  $\mathbb{I}$  we have

$$\{\phi \circ s, \phi \circ t\} = \{s, t\}$$

- 2 and for any  $n \in \mathbb{N}$  we have the colimit



## Directed generic segment

axiomatization of the notion of direction

- A generic segment  $(\mathbb{I}, s, t)$  is said **directed** when for any automorphism  $\phi$  of  $\mathbb{I}$ , we have  $\phi \circ s = s$  and  $\phi \circ t = t$ .
- Any automorphism  $\phi$  of  $\mathbb{I}$  such that  $\phi \circ s = t$  and  $\phi \circ t = s$  is called an **inversion of (the) time (flow)**
- In PoSpc, the generic segment  $\overrightarrow{[0, 1]}$  is directed while the generic segment  $([0, 1], =)$  does not.

the map  $t \mapsto 1 - t$  is an inversion of time

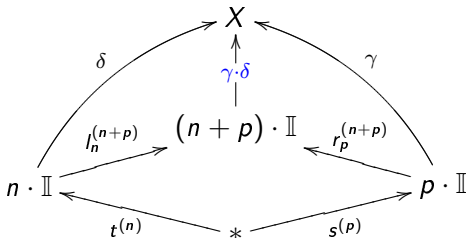
# Category of paths on an object $X$ of $\mathcal{C}$

axiomatization of the notion of *Moore path* (2)

The objects of this category, denoted  $\Gamma(X)$ , are the points of  $X$  and its morphisms, called the **paths on  $X$** , are the elements of

$$\bigcup_{n \in \mathbb{N}} \mathcal{C}[n \cdot \mathbb{I}, X],$$

the source and the target of  $\gamma \in \mathcal{C}[n \cdot \mathbb{I}, X]$  are  $\gamma \circ s^{(n)}$  and  $\gamma \circ t^{(n)}$ ; the **concatenation** being given by the push-out:



# Homotopic congruence over $\mathbb{C}$

axiomatization of the notion of (di)homotopic (di)paths

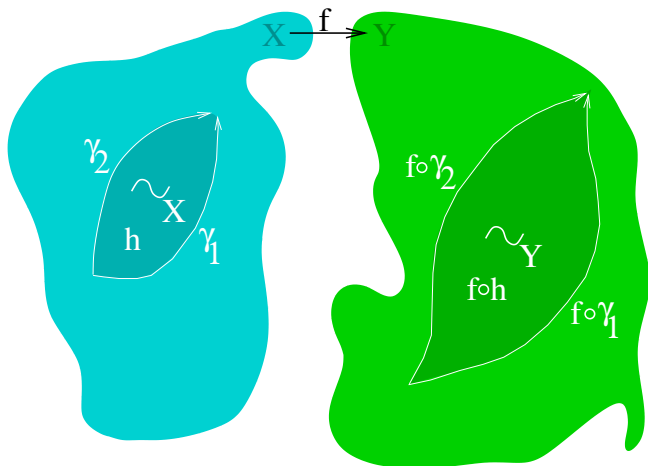
A path  $\gamma \in \mathcal{C}[n \cdot \mathbb{I}, X]$  is said **constant** when it can be written  $\gamma = p \circ \mu$  where  $p$  is a point of  $X$ , it is the **value** of  $\gamma$ .

A **homotopic congruence** on  $\mathbb{C}$  is defined by, **for each object  $X$  of  $\mathbb{C}$** , a congruence  $\sim_X$  on the category of paths on  $X$ , such that for all paths  $\gamma_1$  and  $\gamma_2$  on  $X$ ,

- ① if  $\gamma_1$  and  $\gamma_2$  are constant with the same value, then  $\gamma_1 \sim_X \gamma_2$ ,
- ② if  $\gamma_1 \sim_X \gamma_2$ , then
  - ①  $\gamma_1$  and  $\gamma_2$  share the same extremities and
  - ② for all morphism  $f$  of  $\mathbb{C}$  from  $X$  to  $Y$  we have  $f \circ \gamma_1 \sim_Y f \circ \gamma_2$ .

# Homotopic congruence

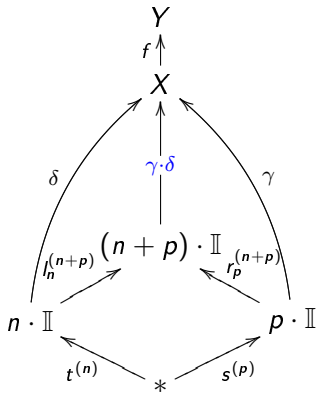
in picture



Think of  $\sim_X$  as “there exists a classic homotopy  $h$  from the paths  $\gamma_1$  to  $\gamma_2$ ”

# Generalized fundamental category

We set  $\vec{\pi}_1(\vec{X}) := \Gamma(X) / \sim_X$  and we have a functor  $\vec{\pi}_1 : \mathbf{C} \rightarrow \mathbf{Cat}$ .



Since  $\gamma_1 \sim_X \gamma_2$  implies  $f \circ \gamma_1 \sim_Y f \circ \gamma_2$ , we can define  $\vec{\pi}_1(\vec{f})[\gamma]_{\sim_X} := [f \circ \gamma]_{\sim_Y}$ , moreover, the left hand side diagram shows that we have  $f \circ (\gamma \cdot \delta) = (f \circ \gamma) \cdot (f \circ \delta)$  whence the functoriality of  $\vec{\pi}_1(\vec{f})$  from  $\vec{\pi}_1(\vec{X})$  to  $\vec{\pi}_1(\vec{Y})$ .

## directed vs undirected generic segment in the framework of PoSpc

- With the generic segment  $([0, 1], =)$  over PoSpc, for any pospace  $\vec{X}$ ,  $\vec{\pi}_1(\vec{X})$  is the fundamental groupoid of  $X$ .
- With the generic segment  $([0, 1], \leq)$  over PoSpc, for any pospace  $\vec{X}$ ,  $\vec{\pi}_1(\vec{X})$  is the fundamental category of  $\vec{X}$ .